



# **MIRA HDR Field Trailer User Guide**

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Please let us know about your use and experience of our products as well as the contents and usefulness of this manual. We're excited to be part of your journey!



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# Table of content

MIRA HDR Field Trailer .....	5
Assembly .....	6
MALÅ MIRA HDR Field Trailer .....	6
Towing Arm .....	7
Wheel Hub .....	8
Skid Plate .....	9
GNSS Frame .....	10
Fitting the MIRA HDR System .....	11
Cables and Connections .....	13
Use and Adjustments .....	14
Use of Remote Control .....	14
Adjust the Measurement Height .....	14
GNSS .....	16
Wheel Encoder .....	17
Software .....	17

## MIRA HDR Field Trailer

MIRA HDR Field Trailer is a carrying solution for the MALÅ MIRA HDR multichannel system. This trailer is intended to be used behind an ATV (4-wheeler) or a car, when carrying out e.g., measurements on agricultural land or grass fields.

On roads the speed limitation of the MIRA HDR Field Trailer (when the antenna box is as its highest position) is 50 km/h (31 mph).

It is the user's responsibility to check what road regulations applies in the investigation area and during transport.



# Assembly

## MIRA HDR Field Trailer

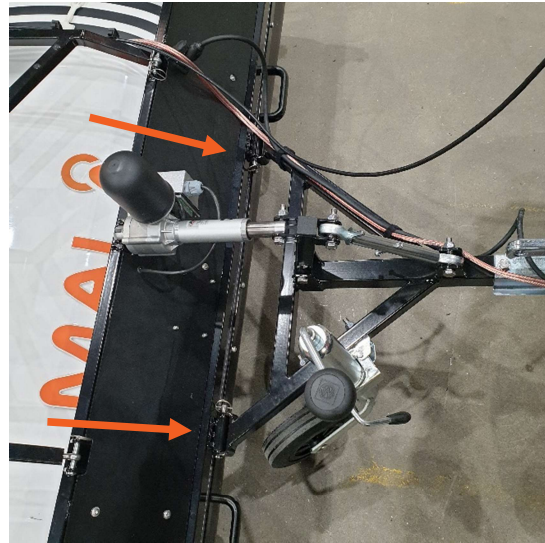
The trailer consists of a main frame (1), towing arm (2), skid plate assembly (3), two wheel hubs (4) and a GNSS frame (5).

The trailer is delivered in four parts: the towing arm, the frame (main frame, skid plate, GNSS frame in one piece) and the two wheel hubs.



## Towing arm

The towing arm is attached to the lower part of the main frame using two clevis pins secured with spring cotter pins.

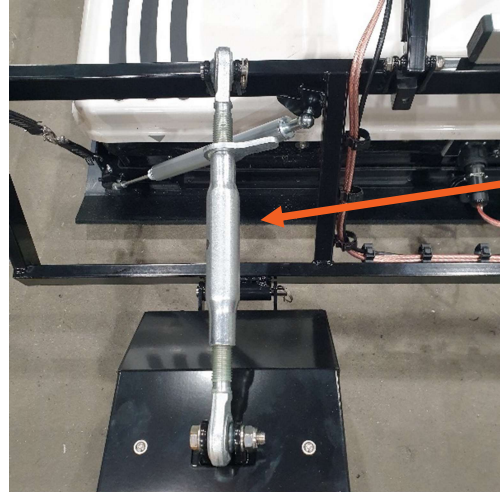


The linear actuator and the adjustable linkage rod are connected to the towing arm top linkage using a bolted connection.



## Wheel hub

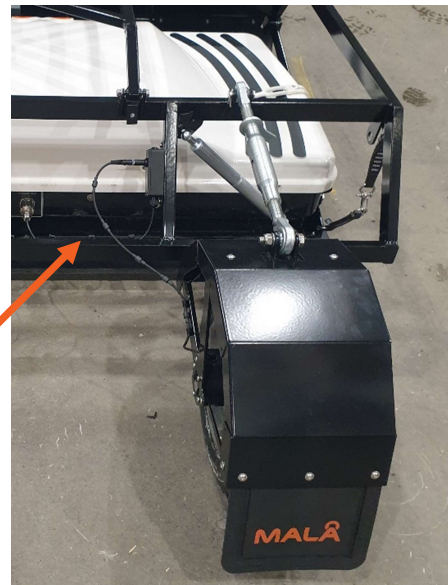
The wheels attach to the main frame using clevis pins and spring cotter pins, and an adjustable linkage rod.



**Note:** One of the wheels has an integrated wheel encoder. This wheel needs to be placed on the right side of the main frame.

The encoder cable connects to a small black box on the main frame close to the wheel mounting point.

See also section *Adjust the measurement height*, for the use of the adjustable linkage rods.



## Skid plate

The skid plate is mounted on delivery.

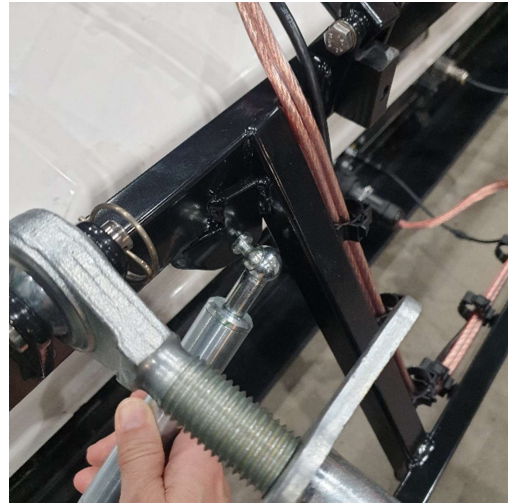
The rubber front part of the skid assembly is attached under the towing arm (in two places) using clevis pins and spring cotter pins.

The linkage arms on the sides are attached to the two front corners of the main frame, using the same type of attachment.

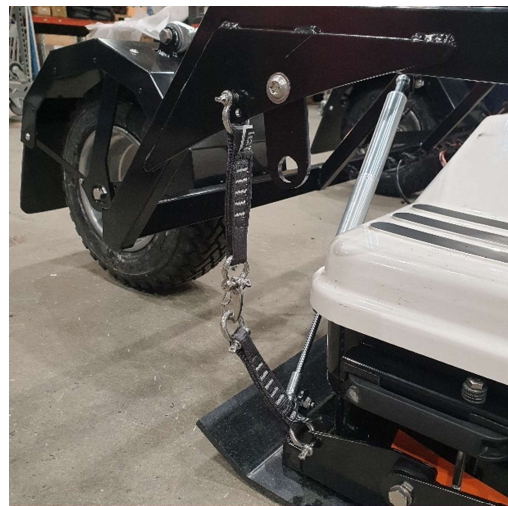


The gas dampers are attached to the ball joints on the upper and lower part of the main frame. The ball point is pressed to the knob on the main frame.

**Note:** The gas dampers are attached with the thicker part up.



To prevent the gas dampers from overextending a safety band is attached using two shackles.

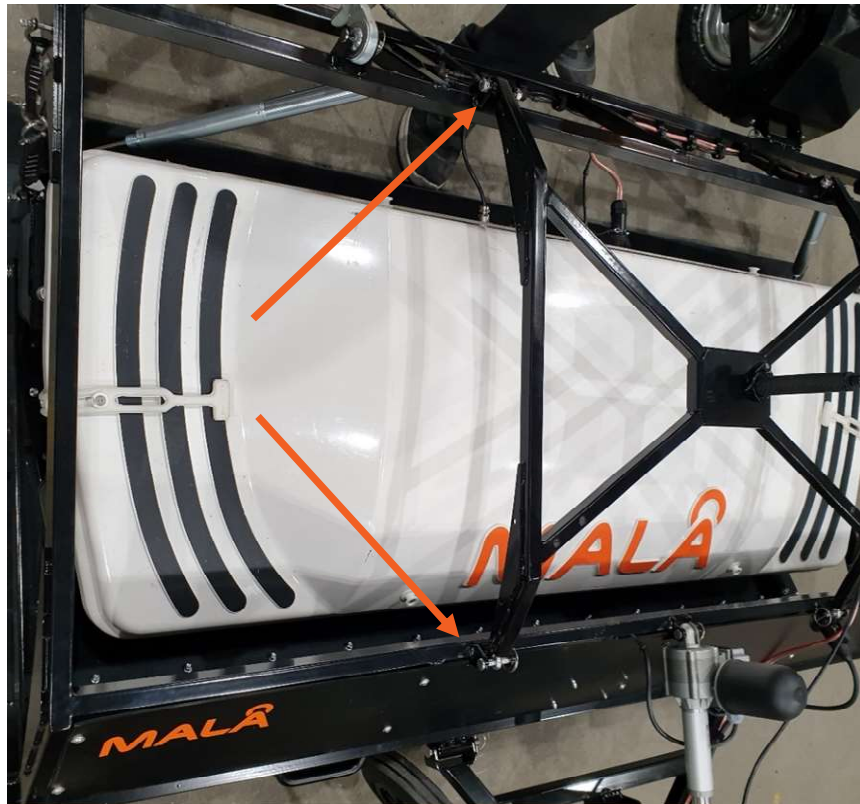


## GNSS frame

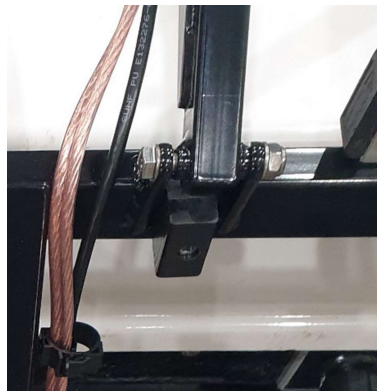
The GNSS frame is mounted on delivery.

The GNSS frame is attached to the main frame using bolts and nuts on the rear side, and pin and spring cotter pins on the front side.

**Note:** It is important to use the correct assembly on each side as this enables you to a quick and easy flip back when mounting the MIRA HDR antenna box.



Front side



Rear side

## Fitting the MIRA HDR system

For efficient mounting of the MIRA HDR system to the MIRA HDR Field Trailer, it is recommended to be two persons.

### Top loading

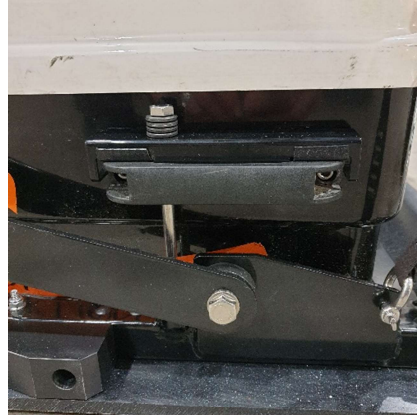
1. Release the GNSS frame front pins and flip it backwards to open the main frame.



2. Carefully lift the MIRA HDR system down through the opening, placing it on the skid plate. Make sure it is placed within the frame and all the way down.



3. Secure the MIRA HDR system using the mounting arms, two on each side.



4. Flip the GNSS frame forward and secure the front pins.
5. See section *Cables and Connections* for connection of needed cables.

### **Skid plate loading**

1. Disassemble the gas damper, the safety bands, the skid plate linkage arms and the skid plate front mounting points.
2. Move the main frame away using the tow-hitch handle to open up the skid plate.
3. Place the MIRA HDR antenna box on the skid plate and secure it using the mounting arms, two on each side. See section *Top loading*.
4. Roll the main frame back over the skid plate and reassemble all parts removed in step 1.
5. See section *Cables and Connections* for connection of needed cables.



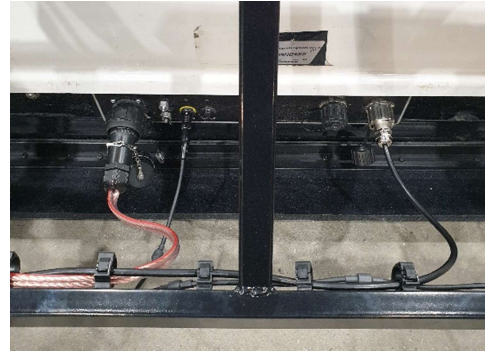
*Skid plate assembly complete, ready for step 4.*

## Cables and connections

Connect the power-, wheel- and Ethernet cable to its corresponding connector on the rear side of the MIRA HDR antenna box.

**Note:** The Ethernet cable is connected to the right-most connector on the MIRA HDR antenna box

Make sure the cables are secured to the main frame.



# Use and adjustments

## Use of remote control

Activate the linear actuator remote by pressing both Up- and Down button and hold for one second.

**Note:** The linear actuator can also be controlled by the up- and down-buttons on the grey box behind the face plate.

**Note:** Do not open the grey plastic box mounted at the front side (behind the face plate) of the MIRA HDR Field Trailer. This exposes the relay and controller for the linear actuator, which are not IP rated.

## Adjust the measurement height

### Preparation

Attach the MIRA HDR Field Trailer to the towing vehicle and find a flat spot. The adjustments are based on the attached vehicle's tow hitch height, so these adjustments need to be repeated when switching vehicle.

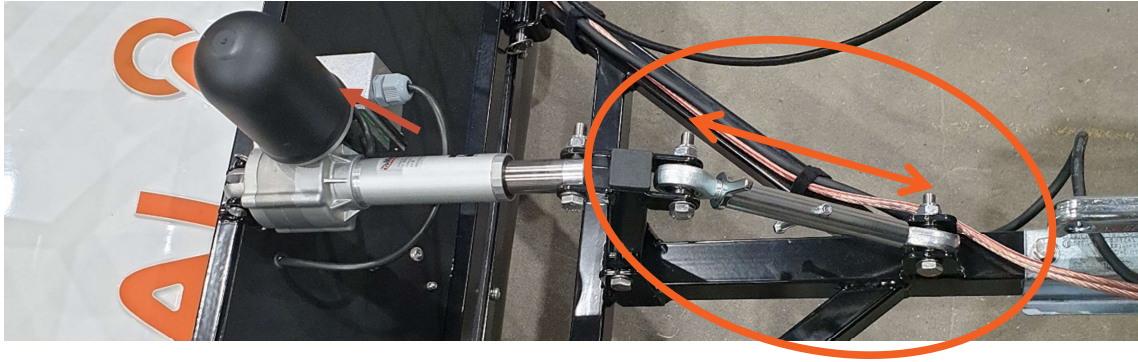
**Note:** If you use a 4-wheeler (ATV) make sure the vehicle is weighed down as in operation before you continue the adjustments to avoid the tow hitch height changing.

### Adjust the angle and measurement height

Adjust the MIRA HDR Field Trailer to your vehicle according to the following steps:

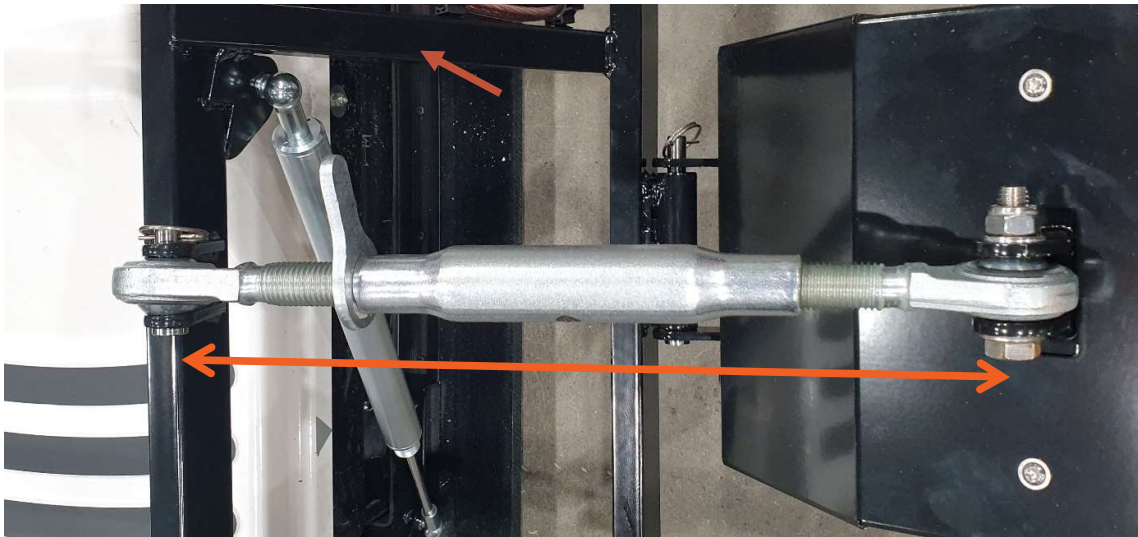
1. Adjust the linear actuator to its minimum position using the remote controller.
2. Adjust the front adjustable linkage rod on the towing arm to get the desired measurement height. Lock the adjustment using the locking nut.

**Note:** Do not adjust beyond 285 mm CC on the front adjustable linkage rod



3. Adjust the adjustable linkage rods on the wheel hubs until the main frame is level with the ground (GNSS pole is vertical). Lock the adjustment using the locking nut with handle.

**Note:** Do not adjust beyond 450 mm CC on the rear adjustable linkage rod



**Note:** Always secure the locking nuts on the linkage rods firmly.

## GNSS

An external GNSS antenna can be attached to the GPS frame quick release attachment point. A short GNSS pole is provided with the system.

If using a long GNSS pole, support arms can be mounted to ensure the pole rigidity.



*GPS support mount*



*GPS support lower mount*

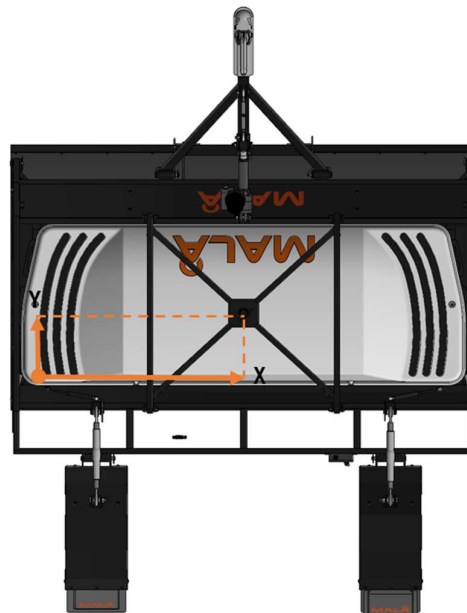


*Assembled GPS support*

## GNSS offset

Use custom setting in MIRAsoft HDR with X 0.777 and Y 0.19.

**Note:** Y may vary depending on the height adjustment and angle of the system. Use values based on your own measurements for higher accuracy.



### **Wheel encoder**

The wheel encoder is located on the right tire and is connected to the system through a connection box on the frame.

The provided wheel encoder needs to be calibrated using MALÅ MIRAsoft HDR. Please refer to the [MALÅ MIRAsoft HDR User Manual](http://www.guidelinegeo.com/MALÅ_MIRAsoft_HDR_User_Manual) at [www.guidelinegeo.com](http://www.guidelinegeo.com).

### **Software**

Make sure to always use the latest version of the acquisition software [MALÅ MIRAsoft HDR](http://www.guidelinegeo.com/MALÅ_MIRAsoft_HDR) available for download from [www.guidelinegeo.com](http://www.guidelinegeo.com).